ATV12HU22M3

variable speed drive ATV12 - 2.2kW - 3hp - 200..240V - 3ph - with heat sink



Main

Range of product	Altivar 12	
Product or component type	Variable speed drive	
Product destination	Asynchronous motors	
Product specific application	Simple machine	
Assembly style	With heat sink	
Component name	ATV12	
Quantity per set	Set of 1	
EMC filter	Without EMC filter	
Built-in fan	With	
Network number of phases	Three phase	
[Us] rated supply voltage	200240 V (- 1510 %)	
Motor power kW	2.2 kW	
Motor power hp	3 hp	
Communication port protocol	Modbus	
Line current	12.5 A at 240 V 14.9 A at 200 V	
Speed range	120	
Transient overtorque	150170 % of nominal motor torque depending on drive rating and type of motor	
Asynchronous motor control profile	Quadratic voltage/frequency ratio Sensorless flux vector control Voltage/Frequency ratio (V/f)	
IP degree of protection	IP20 without blanking plate on upper part	
Noise level	50 dB	

Complementary

Complementary		
Supply frequency	50/60 Hz (+/- 5 %)	
Type of connector	1 RJ45 for Modbus on front face	
Physical interface	2-wire RS 485 for Modbus	
Transmission frame	RTU for Modbus	
Transmission rate	38400 bit/s 19200 bit/s 9600 bit/s 4800 bit/s	
Number of addresses	1247 for Modbus	
Communication service	Read device identification (43) Read/Write multiple registers (23), messaging: 4/4 words maximum Write multiple registers (16), messaging: 27 words maximum Write single register (06), messaging: 29 words maximum Read holding registers (03), messaging: 29 words maximum	
Prospective line Isc	<= 5 kA	
Continuous output current	10 A at 4 kHz	
Maximum transient current	15 A for 60 s	
Speed drive output frequency	0.5400 Hz	
Nominal switching frequency	4 kHz	
Switching frequency	cy 416 kHz with derating factor 216 kHz adjustable	

Braking torque	Up to 70 % of nominal motor torque without braking resistor Up to 150 % of nominal motor torque with braking resistor at high inertia	
Motor slip compensation	Adjustable Preset in factory	
Output voltage	200240 V three phase	
Electrical connection	L1, L2, L3, U, V, W, PA, PC terminal 5.5 mm² (AWG 10)	
Tightening torque	1.2 N.m	
Insulation	Electrical between power and control	
Supply	Internal supply for logic inputs 24 V DC, voltage limits 20.428.8 V, 100 mA for overload and short-circuit protection Internal supply for reference potentiometer 5 V DC, voltage limits 4.755.25 V, 10 mA for overload and short-circuit protection	
Analogue input number	1	
Analogue input type	Al1 configurable voltage 05 V, impedance 30 kOhm Al1 configurable voltage 010 V, impedance 30 kOhm Al1 configurable current 020 mA, impedance 250 Ohm	
Discrete input number	4	
Discrete input type	(LI1LI4) programmable, 24 V, voltage limits 1830 V	
Discrete input logic	Positive logic (source), 0< 5 V (state 0), > 11 V (state 1) Negative logic (sink), > 16 V (state 0), < 10 V (state 1), input impedance 3.5 kOhm	
Sampling duration	< 10 ms for analogue input < 20 ms, tolerance +/- 1 ms for logic input	
Linearity error	+/- 0.3 % of maximum value for analogue input	
Analogue output number	1	
Analogue output type	(AO1) software-configurable current, analogue output range 020 mA, output impedance 800 Ohm, analogue output resolution 8 bits (AO1) software-configurable voltage, analogue output range 010 V, output impedance 470 Ohm, analogue output resolution 8 bits	
Discrete output number	2	
Discrete output type	(R1A, R1B, R1C) protected relay output 1 C/O (LO+, LO-) logic output	
Minimum switching current	5 mA at 24 V DC for logic relay	
Maximum switching current	4 A at 30 V DC resistive load cos phi = 1 L/R = 0 ms for logic relay 3 A at 250 V AC resistive load cos phi = 1 L/R = 0 ms for logic relay 2 A at 30 V DC inductive load cos phi = 0.4 L/R = 7 ms for logic relay 2 A at 250 V AC inductive load cos phi = 0.4 L/R = 7 ms for logic relay	
Acceleration and deceleration ramps	Linear from 0 to 999.9 s	
	S U	
Braking to standstill	By DC injection, 0.130 s	
Protection type	Thermal motor protection via the drive by continuous calculation of I²t Against input phase loss in three-phase Short-circuit between motor phases Overheating protection Overcurrent between output phases and earth Line supply undervoltage Line supply overvoltage	
Frequency resolution	Display unit 0.1 Hz Analog input converter A/D, 10 bits	
Time constant	20 ms, tolerance +/- 1 ms for reference change	
Marking	CE	
Operating position	Vertical +/- 10 degree	
Height	143 mm	
Width	105 mm	
Depth	131.2 mm	
Product weight	1.2 kg	



Environment

Environment	
Electromagnetic compatibility	Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11 Surge immunity test (level 3) conforming to EN/IEC 61000-4-5 Radiated radio-frequency electromagnetic field immunity test (level 3) conforming to EN/IEC 61000-4-3 Immunity to conducted disturbances (level 3) conforming to EN/IEC 61000-4-6 Electrostatic discharge immunity test (level 3) conforming to EN/IEC 61000-4-2 Electrical fast transient/burst immunity test (level 4) conforming to EN/IEC 61000-4-4
Electromagnetic emission	Conducted emissions with additional EMC filter, class: environment 2 category C3 conforming to EN/IEC 61800-3 - test level: 412 kHz, <= 20 m shielded motor cable Conducted emissions with additional EMC filter, class: environment 1 category C2 conforming to EN/IEC 61800-3 - test level: 412 kHz, <= 20 m shielded motor cable Conducted emissions with additional EMC filter, class: environment 1 category C1 conforming to EN/IEC 61800-3 - test level: 412 kHz, <= 5 m shielded motor cable Radiated emissions, class: environment 1 category C2 conforming to EN/IEC 61800-3 - test level: 216 kHz shielded motor cable
Product certifications	CSA C-Tick GOST NOM UL
Vibration resistance	1.5 mm peak to peak (f = 313 Hz) drive unmounted on symmetrical DIN rail conforming to EN/IEC 60068-2-6 1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to EN/IEC 60068-2-27
Relative humidity	595 % without dripping water conforming to IEC 60068-2-3 595 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for storage	-2570 °C
Ambient air temperature for operation	5060 °C with current derating 2.2 % per °C -1050 °C with protective cover from the top of the drive removed
Operating altitude	> 10003000 m with current derating 1 % per 100 m <= 1000 m without derating

Offer Sustainability

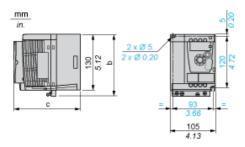
Sustainable offer status	Not Green Premium product
RoHS (date code: YYWW)	Compliant - since 0901 - Schneider Electric declaration of conformity



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Dimensions

Drive without EMC Conformity Kit



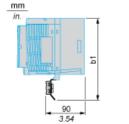
Dimensions in mm

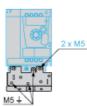
b	С
143	131.2

Dimensions in in.

b	С
5.63	5.16

Drive with EMC Conformity Kit





Dimensions in mm

b1	
189.3	

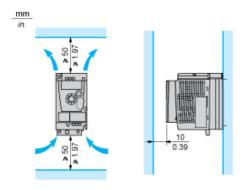
Dimensions in in.

b1	
7.45	

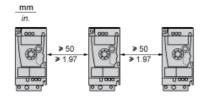
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Mounting Recommendations

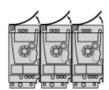
Clearance for Vertical Mounting



Mounting Type A

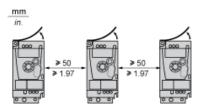


Mounting Type B



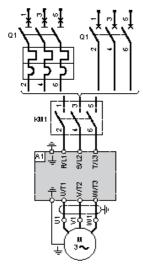
Remove the protective cover from the top of the drive.

Mounting Type C



Remove the protective cover from the top of the drive.

Three-Phase Power Supply Wiring Diagram



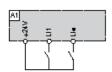
A1 Drive

KM1 Contactor (only if a control circuit is needed)

Q1 Circuit breaker

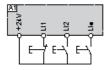
Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply



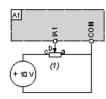
LI1: Forward LI•: Reverse A1: Drive

3-Wire Control for Logic I/O with Internal Power Supply



LI1: Stop LI2: Forward LI•: Reverse A1: Drive

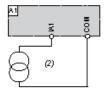
Analog Input Configured for Voltage with Internal Power Supply



(1) 2.2 $k\Omega$...10 $k\Omega$ reference potentiometer

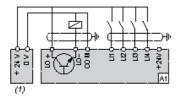
A1: Drive

Analog Input Configured for Current with Internal Power Supply



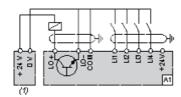
(2) 0-20 mA 4-20 mA supply A1: Drive

Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vdc supply A1: Drive

Connected as Negative Logic (Sink) with External 24 vdc supply

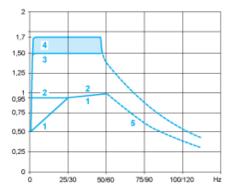


(1) 24 vd A1: Drive 24 vdc supply

Product data sheet Performance Curves

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Torque Curves



- 1: Self-cooled motor: continuous useful torque (1)
- 2: Force-cooled motor: continuous useful torque
- 3: Transient overtorque for 60 s
- 4: Transient overtorque for 2 s
- 5: Torque in overspeed at constant power (2)
- (1) For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
- (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selected motor must be checked with the manufacturer.